CONTACT

Chair of Buiding Realization and Robotics Prof. Prof. h. c./SRSTU Dr.-Ing./Univ.Tokio T. Bock Technische Universität München Arcisstrasse 21 80333 München Tel: +49 89 289 22100 Fax: +49 89 289 22102

www.br2.ar.tum.de Office Management:

thomas.bock@br2.ar.tum.de

Rebekka Schlenker Tel. +49 89 289 22100 Fax: +49 89 289 22102 info@br2.ar.tum.de

Scientific Assistants:

Dipl.-Ing.Thomas Linner Tel. +49 89 289 22178 thomas.linner@br2.ar.tum.de

Dr.-Ing. Christos Georgoulas Tel: +49 89 289 28650 christos.georgoulas@br2.ar.tum.de

Dipl.-Inf. Furkan Eke Tel: +49 89 289 22100 furkan.eke@br2.ar.tum.de

M.Sc.-Ing. Sarah Klein Tel: +49 89 289 22170 sarah.klein@br2.ar.tum.de

Prof. Dr. Med. Kerstin Wessia Tel: +49 89 289 22100 kerstin.wessig@br2.ar.tum.de

Mechatronics Technician:

Andreas Bittner Tel: +49 89 289 22482 andreas.bittner@br2.ar.tum.de

Guest Researchers:

Prof. Dr. Kazuvoshi Endo Tel: +49 89 289 22100 kazu endo 0805@ac.cvberhome.ne.ip

Prof. Dr.-Ing. hab. Alexej Bulgakow Tel: +49 89 289 22100 info@br2 ar tum de

Dr. Shabtai Isaac Tel: +49 89 289 22100 isaacsh@bgu.ac.il

Kepa Ituralde Tel: +49 89 289 22100 kepaiturralde@coavn.org

Assistant Lecturers

Construction Lawver Thomas Richter Tel: +49 89 289 22100

Prof. Dr. Habil, Peter Eduard Mayer Tel: +49 89 289 22100 info@br2.ar.tum.de pe.mayer@br2.ar.tum.de

Min.Rat Dipl.Ing. Friedrich Amann Tel: +49 89 289 22100 info@br2.ar.tum.de

Min.Rat Prof. Dipl.-Ing. Herbert Kallmayer Tel: +49 89 289 22100 info@br2.ar.tum.de

Our Research Expertise

Robot Oriented Design & Management



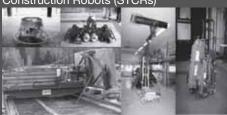
Building Component Manufacturing (BCM)



Large Scale Prefabrication (LSP)



Site Logistics and Single Task Construction Robots (STCRs)



Our Vision

Automated manufacturing technology that accompanies a shift from an arts and crafts based industry to an industry based on systematization and machine technology needs to be able to not only improve or double productivity, but to multiply performance (e.g. reduction of construction time to 1/10th compared to conventional construction, zerowaste, and defect free products). We envision a construction industry which is able to produce or change

Automated/Robotic On-site Factories



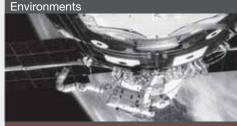
Hummanoids & Exoskeleton Technology in Construction



Automated Deconstruction, Re-Customization & Recycling



Automation & Robotics in extreme



buildings according to customer demands with minimal delay in a near real time manner. Individual subsystems of the on -site factory, as well as sensor systems necessary to guide automated logistics and positioning operations on-site, can be integrated as building technology into the building and re-activated for change, recustomization and deconstruction during the building's life cycle. This idea we formalized into a life-cycle and building integrated manufacturing concept.



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Approach

Productivity and efficiency in the conventional labor based construction industry in Germany, Japan and the USA has been declining for about two decades. In comparison, productivity and efficiency in most other industries (e.g. in the manufacturing industry) has constantly been on the rise during that time period. The decline of productivity since the 1990s has coincided with a worldwide re-orientation in construction from technological based construction towards labor based management and organization oriented approaches.

As of today, major construction companies and many other practitioners and researchers have been seeking the solution for better productivity in construction, and even again increasingly in better management and organization of the conventional laborintensive construction method. However, this approach sharply contradicts the logic and possibility of industrial and technological advances in manufacturing and only generates marginal improvements. Therefore, our institute follows a radically different approach by focusing on the deployment of automation and robot technology on all levels in construction. We see the construction industry as a manufacturing industry that can produces products with highest efficiency on bases of the best available technologies.

Novel manufacturing technologies in construction and in particular radical solutions require drastic and co-adapted change of manufacturing, technology, organization, products and associated business models in construction. Although the necessary changes and resources are enormous, they can be accomplished on basis of so far developed technologies. The overcoming of associated challenges can eventually turn the construction industry into an incubator for future man-ufacturing technology.

Our Research Facilities

Construction Robotics Laboratory



Since 1990, a multitude of automated highrise sites have been operated by various Japanese companies in Asia. Also in European construction firms, flexible siteautomation systems have been adopted nowadays. Most of these achievements have been obtained by highly experimental research approaches. Therefore the Construction Robotics Laboratory and the Teleconstruction Site in Garching are designed as an experimenting laboratory, i. e. an "Incubator". Incubators are used in innovation science and the R&D-industry to specifically generate inventions or to systemize the invention process.

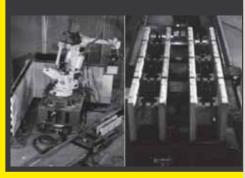
Teleconstruction Site



Tele Construction Experimenting Site is an experimenting site located at Garching Campus, used for multiple purposes. The site is open for students and researchers to implement mock ups, experimental buildings, tele-construction experiments, distinguish and apply various demonstrator/prototype evaluation methods, use evaluation feedbacks for further development of the project in subsequent evaluation-development cycles.

Selected Projects

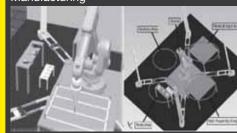
R&D: SMAS (Solid Material Assembling System)



R&D: ROCCO (Robot Construction System for Computer Intergrated Construction)



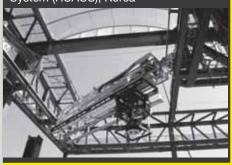
R&D: ManuBuild - Open Building Manufacturing



Strategic Consultancy: Sekisui Chemical Corporation, Housing Division (Sekisui Heim), Japan



Technological Consultancy: Robotic and Crane based Automatic Construction System (RCACS), Korea



Empiric Studies: Automated Deconstruction & Renovation



R&D: SMARTSITE – Smart and Autonomous Construction Equipment.



Future Concepts Development:
Real-Time Construction

